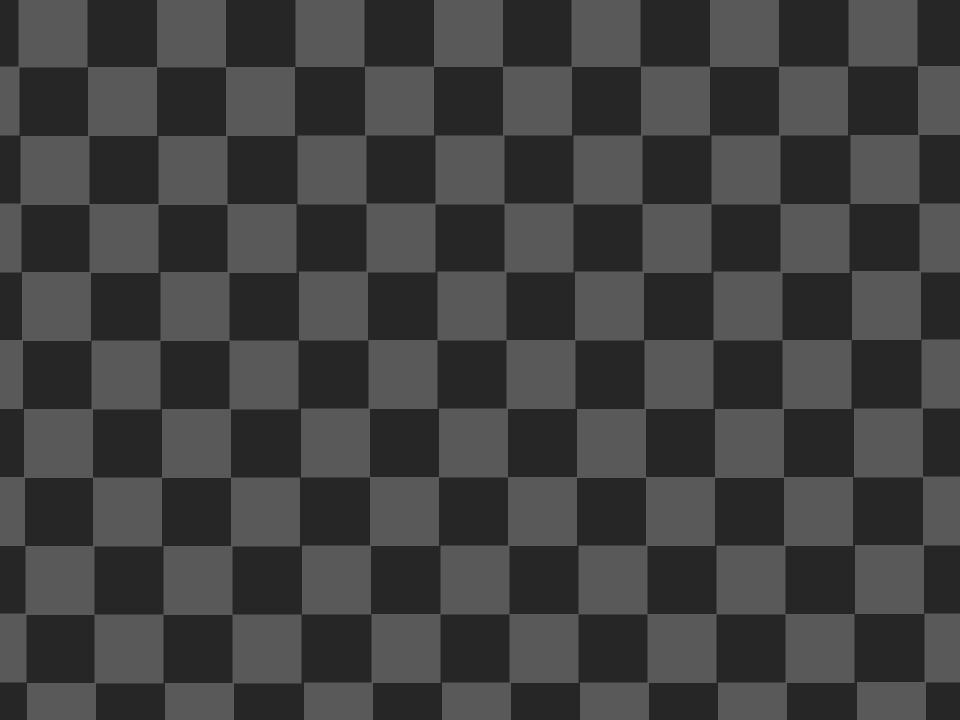
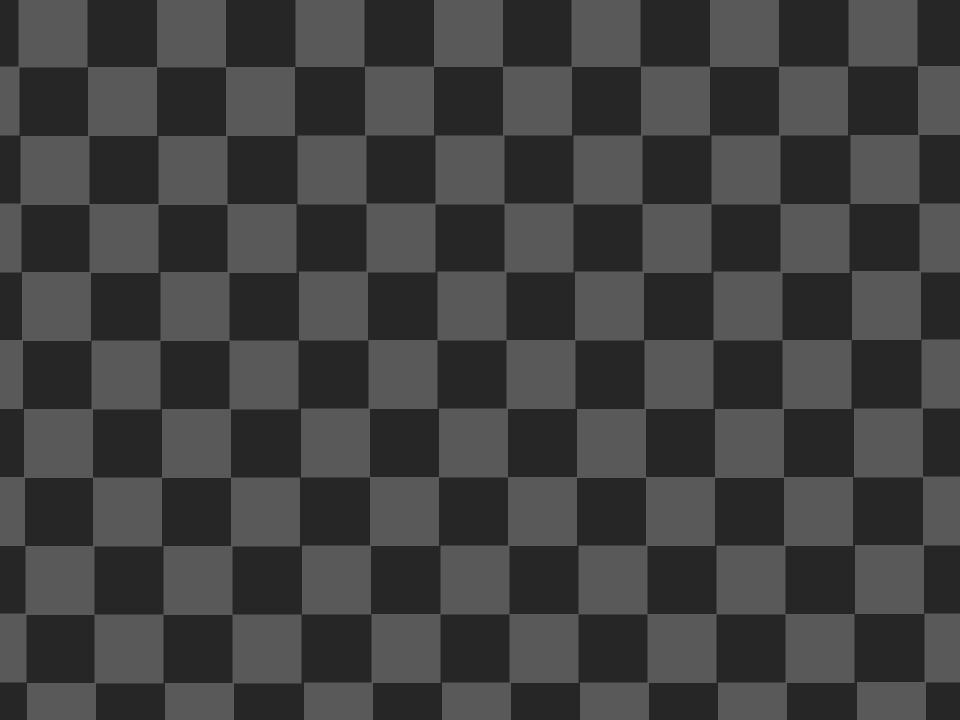
# Generic Tools Specific Languages On the Art of Software Development Tools

Markus Voelter independent/itemis

http://voelter.de voelter@acm.org @markusvoelter



- Tools 4 GTSL
- 2 Extensibilit 5 An Example
- 3 hallenges 6 Wrap Up

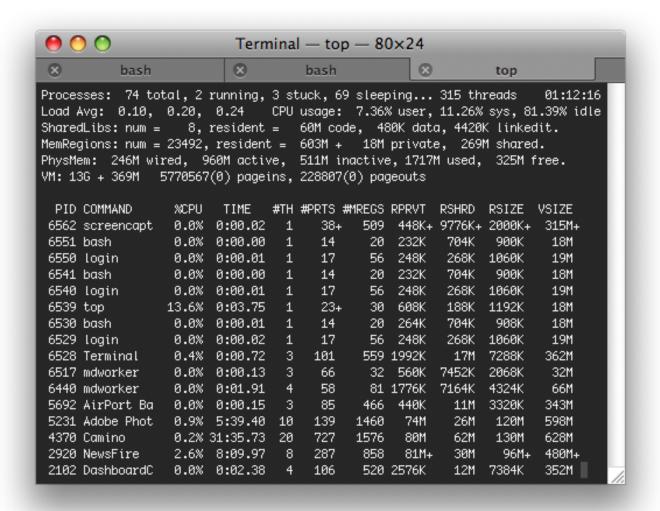




### Toos

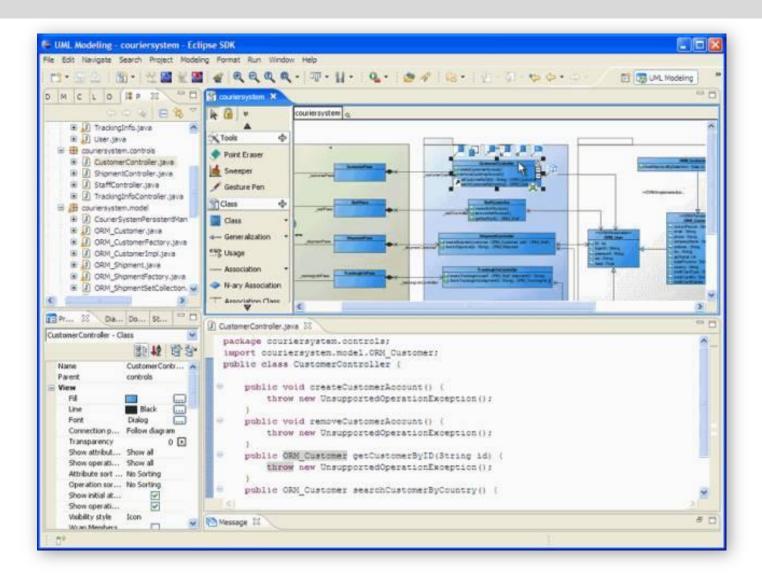
#### **Tools**

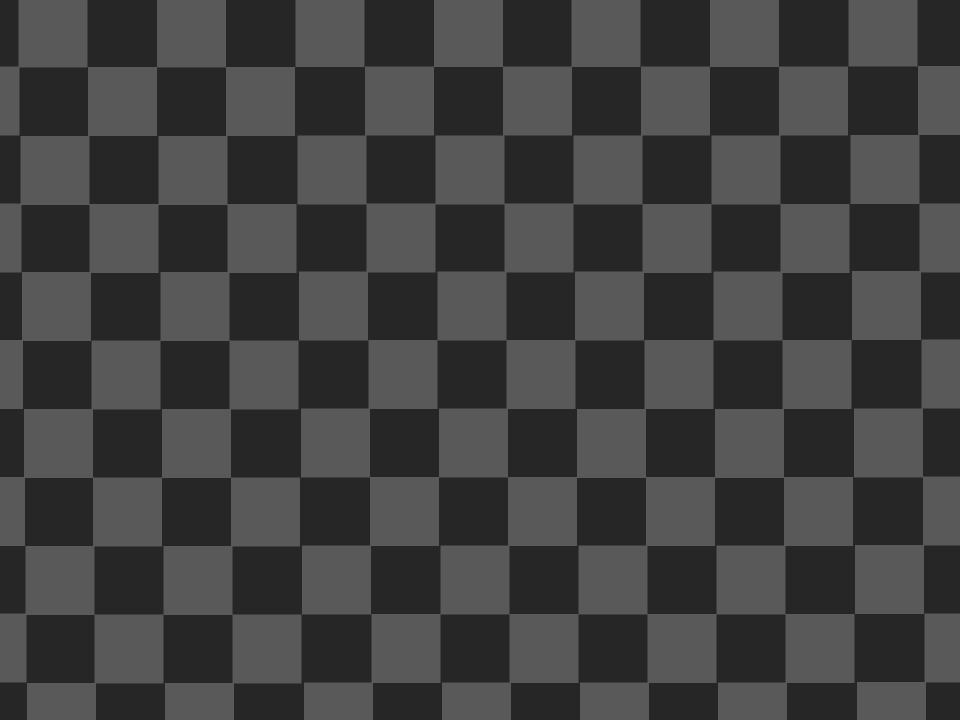
#### **Command-Line Tools**



#### **Tools**

#### **UI Tools**



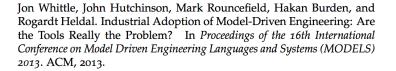




Tool

#### **Study Findings I**

The majority of our interviewees were very successful with MDE but all of them either built their own modeling tools, made heavy adaptations of off-theshelf tools, or spent a lot of time finding ways to work around tools. The only accounts of easy-to-use, intuitive tools came from those who had developed tools themselves for bespoke purposes. Indeed, this suggests that current tools are a barrier to success rather than an enabler.



#### **Study Findings II**

Complexity problems are typically associated with offthe- shelf tools. Of particular note is accidental complexity – which can be introduced due to poor consideration of other categories, such as lack of flexibility to adapt the tools to a company's own context [..]

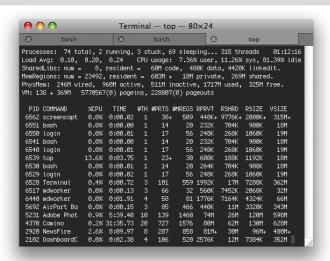
Jon Whittle, John Hutchinson, Mark Rouncefield, Hakan Burden, and Rogardt Heldal. Industrial Adoption of Model-Driven Engineering: Are the Tools Really the Problem? In *Proceedings of the 16th International Conference on Model Driven Engineering Languages and Systems (MODELS)* 2013. ACM, 2013.

#### **Study Findings III**

Our interviews point to a strong need for tailoring of some sort: either tailor the tool to the process, tailor the process to the tool, or build your own tool that naturally fits your own process. Based on our data, it seems that, on balance, it is currently much easier to do the latter.

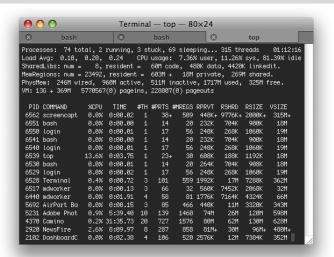
Jon Whittle, John Hutchinson, Mark Rouncefield, Hakan Burden, and Rogardt Heldal. Industrial Adoption of Model-Driven Engineering: Are the Tools Really the Problem? In *Proceedings of the 16th International Conference on Model Driven Engineering Languages and Systems (MODELS)* 2013. ACM, 2013.

#### **Command-Line Tools**



### New File Formats New Processors

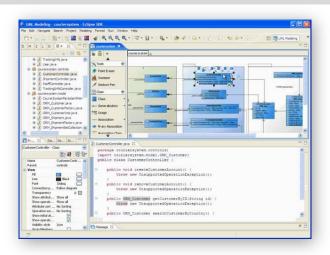
#### **Command-Line Tools**



## New File Formats New Processors

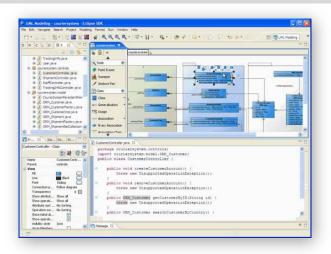
**Assemble Components (Pipes & Filters)** 

#### **UI Tools**



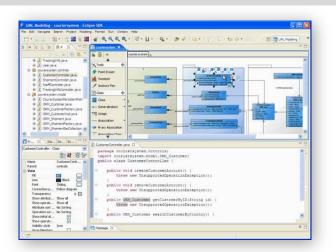
### Buttons Views Menus Actions

#### **UI Tools**



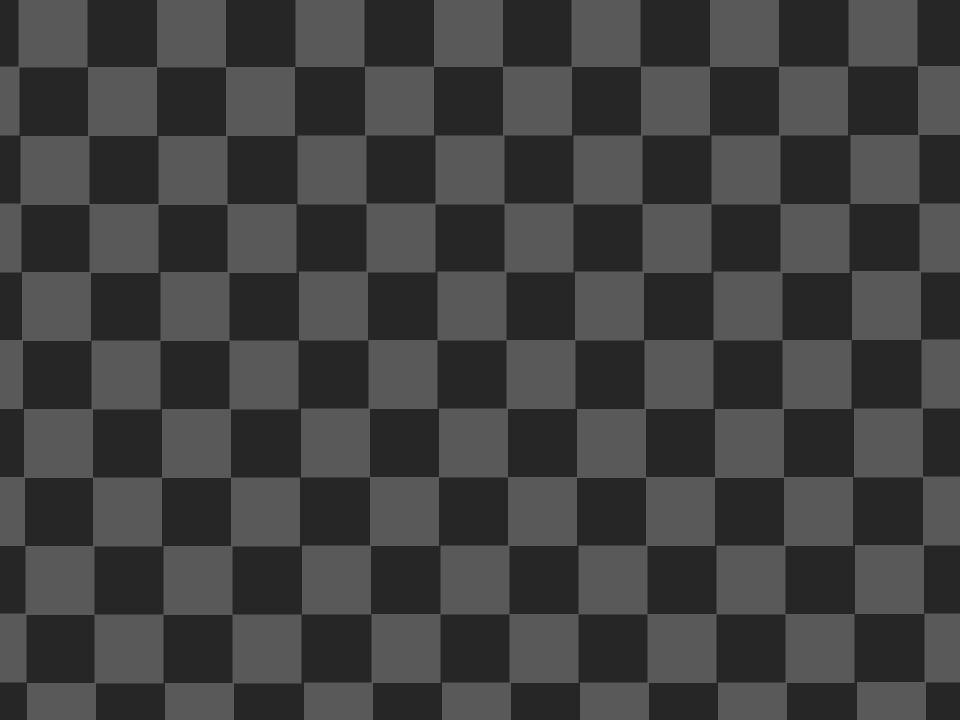
Buttons Views
Menus Actions
New Languages
New Editors

#### **UI Tools**



Buttons Views
Menus Actions
New Languages
New Editors

Platform/Plugin Systems





### Challenges

#### Overview

#### Context: embedded programming

Examples are from Embedde Programming and use C as the "data format"

But applies similarly to other or other data formats/language

**Physical Units: The Challenge** 

How do you work with physical units in your

#### **Physical Units: The Challenge**

```
// in file example.c
int distance = 10;
int time = 1;
int speed = distance / time;
```

#### **Physical Units: The Challenge**

```
// in file example.c
int distance = 10;
int time = 1;
int speed = distance / time;
int speed = time / distance;
How do you detect this e
```

#### **Physical Units: The Challenge**

```
int speed = time / distance;
How do you detect this er
```

YoTope(#oldo the checking)
Data (the units in the code)

#### **Physical Units via Comments**

```
int/*#m*/ distance = 10 /*#m*/;
int/*#s*/ time = 1 /*#s*/;
int/*#mps*/ speed = distance / time;
```



#### **Physical Units via Macros**

```
UT(int, m) distance = UV(10, s);
UT(int, s) time = UV(1, s);
UT(int, mps) speed = distance / time;
```



#### **Physical Units via external XML**

```
<unitdeclarations>
 <unit name="m" for="distance"/>
 <unit name="s" for="time"/>
 <unit name="mps" for="speed" calculateAs="m/s"/>
</unitdeclarations>
cprogrammarkup>
 <globalvar file="example.c" name="distance" unit="m"/>
 <globalvar file="example.c" name="time" unit="s"/>
 <globalvar file="example.c" name="speed" unit="mps"/>
```

#### **Physical Units via Extension**

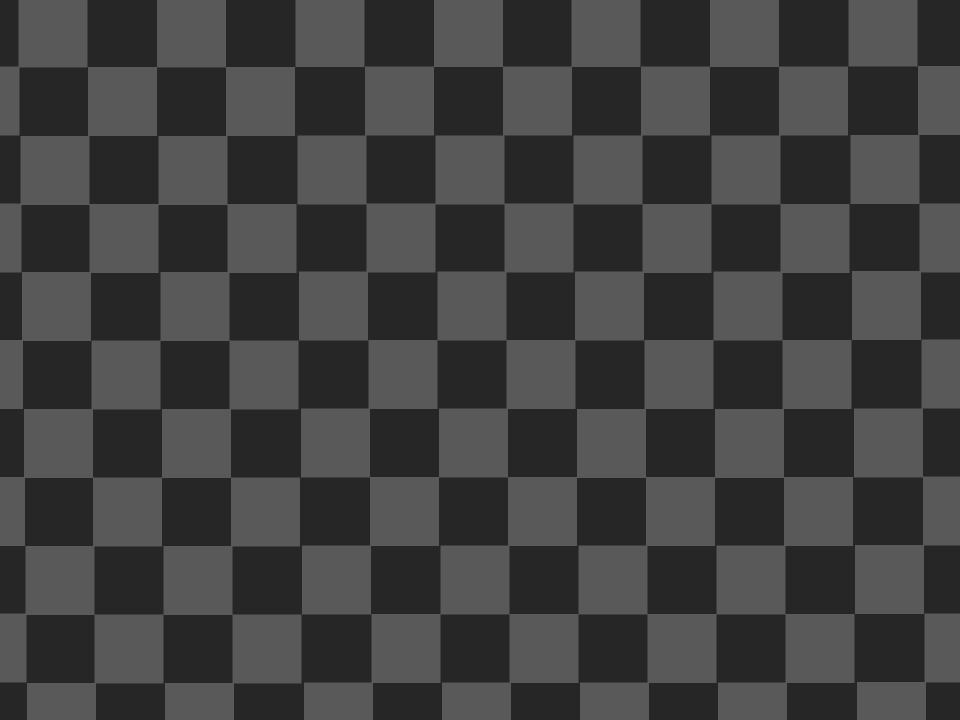
```
int/m/ distance = 10 m;
int/s/ time = 1 s;
int/mps/ speed = distance / time;
```



#### **Physical Units via Extension**

```
int/m/ distance = 10 m;
int/s/ time = 1 s;
int/mps/ speed = distance / time;
```

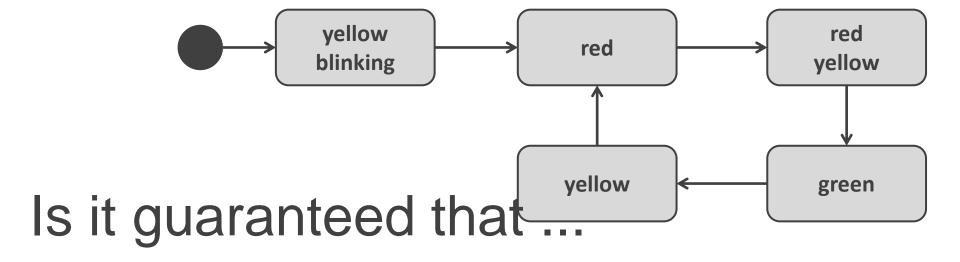
YoTygetChecker (to do the checking)
Program Code (the units in the code)



**State Machines: The Challenge** 

How do you represent state-based behavior and support analyses

#### **State Machines: The Challenge**



- ... the TL get green eventually?
- ... if the TL is turned off/on, it starts in
- ... the TL never goes from yellow to g

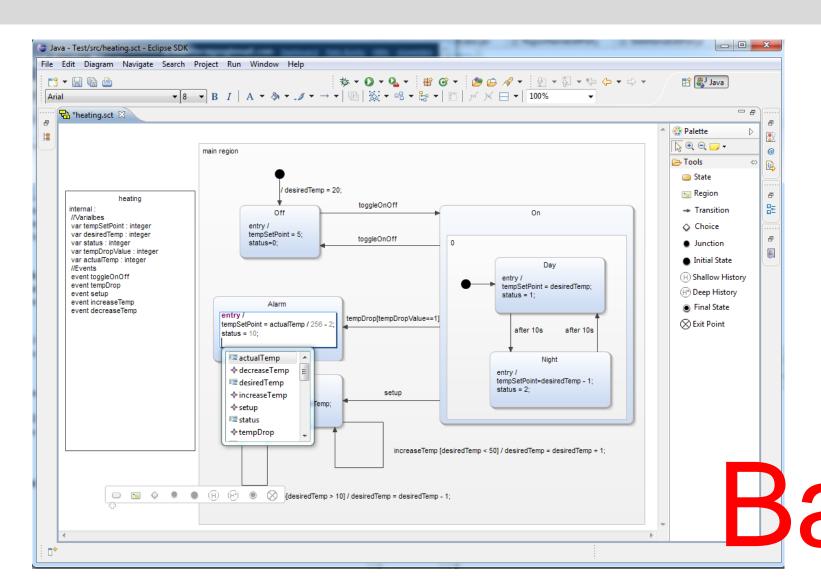
#### State Machines via C idioms

```
// a state machine that transitions into S2
// when E1 is received while the machine is in S1
void execute_StateMachine( Event_Enum evt ) {
  switch (currentState) {
    case S1: switch (evt) {
               case E1: if ( guard for E1 in S1 ) {
                          // execute exit actions for S1
                          currentState = S2;
                          // execute entry actions for S2
                          break;
    case S2:
    . . .
```

#### State Machines via C idioms

Bac

#### **State Machines via External Tool**



**State Machines: The Challenge** 

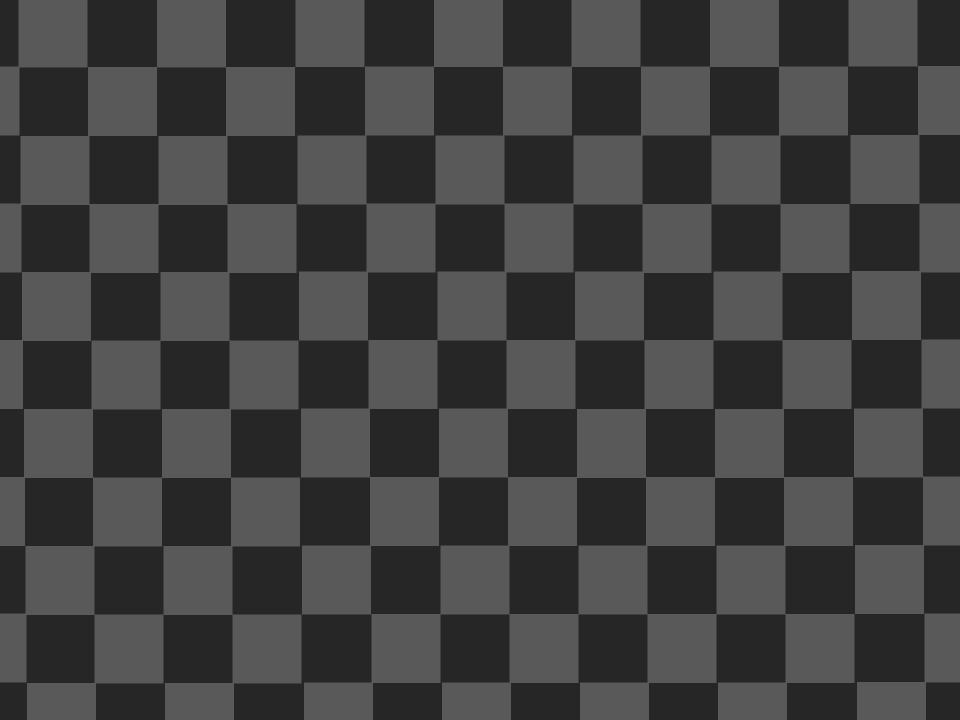
How do you perform anlyses on state machin YoTope(to do the checking) Data ("clean" state machines)

#### **State Machines via Extensions**

```
statemachine SM {
 event E1
 state S1 {
   entry { // entry action for S1 }
   on E1 [guard for E1 in S1] -> S2
   exit { // exit action for S1 }
 state S2 {
                               Good
```

#### **State Machines via Extensions**

```
statemachine SM {
 event E1
 state S1 {
  entry { // entry action for S1 }
  on E1 [guard for E1 in S1] -> S2
  exit { // exit action for S1 }
 state S2
        YConstaint Checker (to do
          the checking)
          Program Code (the units in
          the code)
```



**Tracing: The Challenge** 

How do you add trace requirements anywher your code, robustly?

#### **Tracing via Macros**

```
TRACE(REQ_CALIBRATION)
int calibrate( int measurement ) {
  return measurement * FACTOR + OFFSET;
int getValue() {
  int raw = readFromDriver(ADC1_ADDRESS);
  TRACE(REQ_CALIBRATION)
  return calibrate(raw);
```

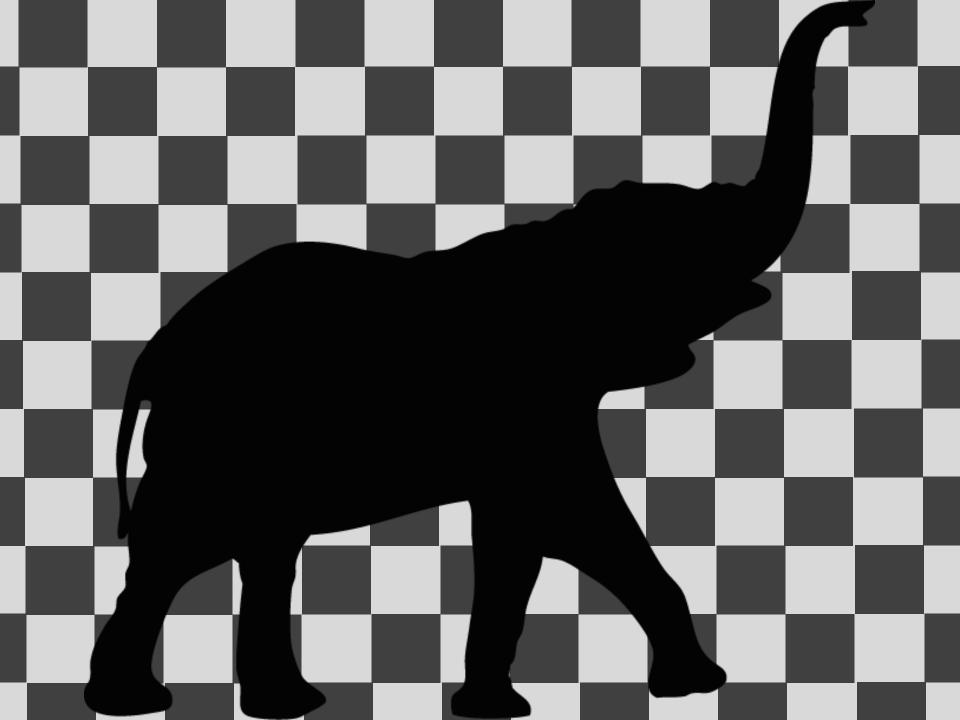
#### **Tracing via Macros**

```
TRACE(REQ_CALIBRATION)
int calibrate( int measurement ) {
   return measurement * FACTOR + OFFSET;
}
int getValue() {
   int raw = readFromDriver(ADC1_ADDRESS);
   TRACE(REQ_CALIBRATION)
   return calibrate(raw);
}
```

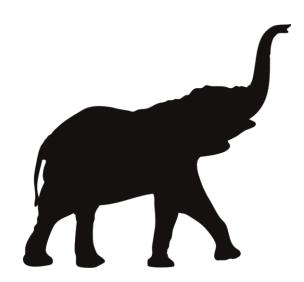
YoTopb(tolcreate trace reports)
Data (robust trace annotations)

#### **Tracing via Language Extensions**

You get the idea :-)



#### **Combinations**



How do you combine these (and other) extenions?

#### **Combinations**

```
statemachine TrainDoorController {
  event DOOR_BUTTON;
  state DOORS_CLOSED {
    trace REQ_BUTTON_OPENS_DOORS_ONLY_OPEN_WHEN_STOPPED
   on DOOR_BUTTON [speed > 0 mps] -> DOORS_OPEN
  state DOORS_OPEN {
   entry { openDoors(); }
   trace REQ_BUTTON_CLOSES_DOORS_WHEN_OPEN
    on DOOR_BUTTON [] -> DOORS_CLOSED
   exit { closeDoors(); }
```

#### **Combinations**

```
statemachine TrainDoorController {
  event DOOR_BUTTON;
  state DOORS_CLOSED {
    trace REQ_BUTTON_OPENS_DOORS_ONLY_OPEN_WHEN_STOPPED
   on DOOR_BUTTON [speed > 0 mps] -> DOORS_OPEN
  state DOORS_OPEN {
   entry { openDoors(); }
   trace REQ_BUTTON_CLOSES_DOORS_WHEN_OPEN
   on DOOR_BUTTON [] -> DOORS_CLOSED
   exit { closeDoors(); }
```

#### **Combinations**

statemachine TrainDoorController { event DOOR\_BUTTON; state DOORS\_CLOSED { trace REQ\_BUTTON\_OPENS\_DOORS\_ONLY\_OPEN\_WHEN\_STOPPED on DOOR\_BUTTON [speed > 0 mps] -> DOORS\_OPEN state DOORS\_OPEN { entry { openDoors(); } trace REQ\_BUTTON\_CLOSES\_DOORS\_WHEN\_OPEN on DOOR\_BUTTON [] -> DOORS\_CLOSED exit { closeDoors(); }

#### **Combinations**

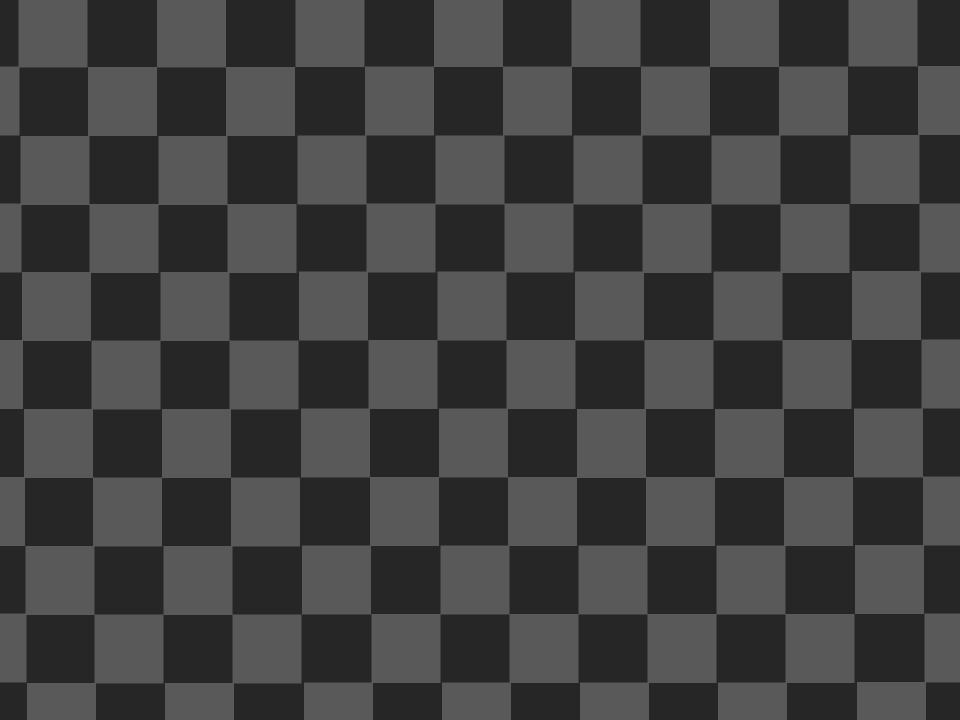
```
statemachine TrainDoorController {
 event DOOR_BUTTON;
 state DOORS_CLOSED {
   trace REQ_BUTTON_OPENS_DOORS_ONLY_OPEN_WHEN_STOPPED
   on DOOR_BUTTON [speed > 0 mps] -> DOORS_OPEN
                                                Tracin
 state DOORS_OPEN {
   entry { openDoors(); }
   trace REQ_BUTTON_CLOSES_DOORS_WHEN_OPEN
   on DOOR_BUTTON [] -> DOORS_CLOSED
   exit { closeDoors(); }
```

#### **Combinations**

```
statemachine TrainDoorController {
 event DOOR_BUTTON;
 state DOORS_CLOSED {
   trace REQ_BUTTON_OPENS_DOORS_ONLY_OPEN_WHEN_STOPPED
   on DOOR_BUTTON [speed > 0 mps] -> DOORS_OPEN
 state DOORS_OPEN {
   entry { openDoors(); }
   trace REQ_BUTTON_CLOSES_DOORS_WHEN_OPEN
   on DOOR_BUTTON [] -> DOORS_CLOSED
   exit { closeDoors(); }
```

#### **Combinations (in an actual tool)**

```
[verifiable]
// This state machine implements a way to grade flights.
   It has separate states for the important flight phases,
  such as @child(beforeFlight) or @child(airborne).
statemachine FlightAnalyzer initial = beforeFlight {
  in next(Trackpoint* tp) <no binding>
  in reset() <no binding>
  out crashNotification() => raiseAlarm
  readable var int16 points = 0
  state beforeFlight {
    //[Here is a comment on a transition.]
    on next [tp->alt == 0 m] -> airborne
    [exit { points += TAKEOFF; }]-> implements PointsForTakeoff
  state beforeFlight
  // This represents the state in which the airplane flies.
     It has several substates. Note how it uses the @top(VERY HIGH SPEED)
     and @top(HIGH_SPEED) constants. These constants are defined in the
     same module @module(StateMachines).
  state airborne {
    on next [tp->alt == 0 m && tp->speed == 0 mps] -> crashed
    on next [tp->alt == 0 m && tp->speed > 0 mps] -> landing
    [on next [tp->speed > 200 mps && tp->alt == 0 m] -> airborne { points += VERY HIGH SPEED; }]-> implements FasterThan200
    on next [tp->speed > 100 mps && tp->speed <= 200 mps && tp->alt == 0 m] -> airborne -> implements FasterThan100
        { points += HIGH_SPEED; }
    on reset [ ] -> beforeFlight
  } state airborne
```

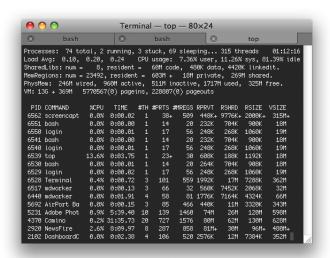


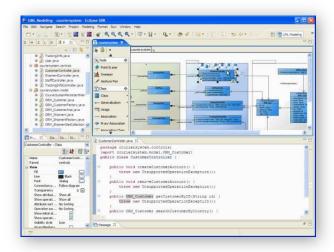
#### **Tool Extension is not enough!**

**Tool Extension is not enough!** 

# Focus on the data first!

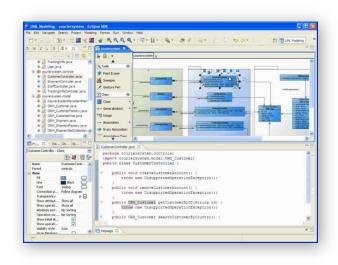
#### **Tool Extension is not enough!**





# These both do not explicitly support

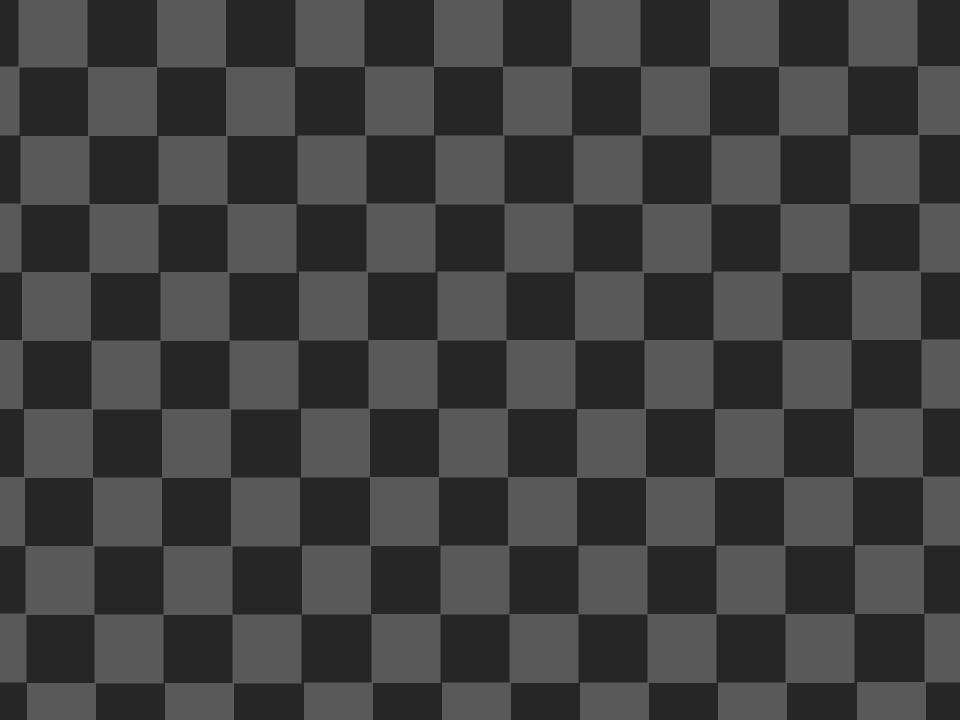
#### **Tool Extension is not enough!**



# Relatively high effort to reimple-ment editors

**Tool Extension is not enough!** 

# Focus on the data first!





## Generic TS LSpecifi Tool ST S Langua

#### From Data Formats To Languages

#### From Data Formats To Languages

### Structure, Constraints, Sema

#### **Data Format**

From Data Formats To Languages

### Structure, Constraints, Sema

Data Format + Syntax

Language

#### From Data Formats To Languages

Languages

Language Engineering

Language Rei Languages Language Modularization Language Composition

Language Engineering

Language Ret Languages Language Modularization Language Compositionering

#### **Language Engineering**

Languages

Language Engineering

#### Language Engineering

Languages

Language Engineering

Text Math Graph TableSymb ics ols Forms

#### Language Engineering

Languages

Language Engineering

Text Math Graph
TableSymb ics

s ols Forms
Syntactic Diversity

#### Language Engineering

Languages

Language Engineering

**Syntactic Diversity** 

#### Language Workbenches

Languages

Language Engineering

**Syntactic Diversity** 

But does this really work?

#### Language Workbenches

Languages

Language Engineering

**Syntactic Diversity** 

But does this really work?
Language Workbenches

#### Language Workbenches

Languages

Language Engineering

**Syntactic Diversity** 

Language Workbenches

Ingredients

Languages

Language Engineering

**Syntactic Diversity** 

Language Workbenches

**Ingredients** 

Specific Language

Languages

Language Engineering

**Syntactic Diversity** 

Generic Tools

Language Workbenches

**Ingredients** 

Specific Language

Languages

Language Engineering

**Syntactic Diversity** 

Generic Tools

Language Workbenches (we don't have to reimplement editors and synchronizers)

**Ingredients** 

Specific Language

Languages

Language Engineering

**Syntactic Diversity** 

support 1

**Generic Tools** 

Language Workbenches

#### **Typical Features**



**Typical Features** 

Language Definition, Reuse, Extension, Composition

**Typical Features** 

Language Definition, Reuse, Extension, Composition Mixing Notations

**Typical Features** 

Language Definition, Reuse, Extension, Composition Mixing Notations, Constraints, Transformation, Interpretation

**Typical Features** 

Goto Definition/Find Usages

**Typical Features** 

Goto Definition/Find

BrageMarkup/Quick

Fixes

**Typical Features** 

Goto Definition/Find
BrageVarkup/Quick
Fixes
Syntax Highlighting

**Typical Features** 

Goto Definition/Find

Brage Varkup/Quick

Fixes
Syntax Highlighting

Code Completion

**Typical Features** 

**Goto Definition/Find** Brage darkup/Quick **Fixes Syntax Highlighting Code Completion** Search/Replace

**Typical Features** 

**Goto Definition/Find** Brage darkup/Quick **Fixes Syntax Highlighting Code Completion** Search/Replace Refactoring

**Typical Features** 

**Goto Definition/Find** Brage darkup/Quick **Eixes Syntax Highlighting Code Completion** Search/Replace Refactoring Debugging

**Typical Features** 

**Goto Definition/Find** Brage darkup/Quick **Fixes Syntax Highlighting Code Completion** Search/Replaceeporting Refactoring Debugging

**Typical Features** 

**Goto Definition/Find** Brage darkup/Quick **Fixes Syntax Highlighting Code Completion** Search/Replaceeporting RefactoringVisualization Debugging

**Typical Features** 

**Goto Definition/Find** Brage darkup/Quick **Fixes Syntax Highlighting Code Completion** Search/Replaceeporting Refactoring Visualization Version Debugging

#### **Typical Features**

# for any Language!

#### **Typical Features**

Language Workbenches are IDEs for arbitrary languages.

#### **Contribute Customizations**



#### **Contribute Customizations**

Language Definition, Reuse, Extension, Composition Mixing Notations, Constraints, Transformation, Interpretation

**Contribute Customizations** 

Goto Definition/Find Brage Markup/Quick **Fixes Syntax Highlighting Code Completion** Search/ReplacReporting Refactoring Visualization Version Debugging

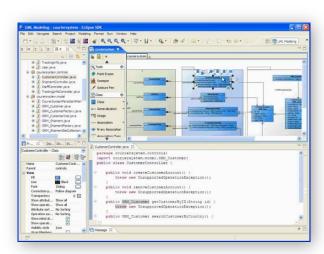
#### **Additional Stuff**

漢字

## Buttons Views Menus Actions

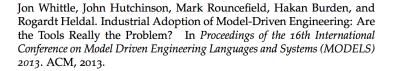
漢





#### **Study Findings I**

The majority of our interviewees were very successful with MDE but all of them either built their own modeling tools, made heavy adaptations of off-theshelf tools, or spent a lot of time finding ways to work around tools. The only accounts of easy-to-use, intuitive tools came from those who had developed tools themselves for bespoke purposes. Indeed, this suggests that current tools are a barrier to success rather than an enabler.



#### **Study Findings I**

The majority of our interviewees were very successful with MDE but all of them either built their own modeling tools, made heavy adaptations of off-theshelf tools, or spent a lot of time finding ways to work around tools. The only accounts of easy-to-use, intuitive tools came from those who had developed tools themselves for bespoke purposes. Indeed, this suggests that current tools are a barrier to success rather than an enabler.

Jon Whittle, John Hutchinson, Mark Rouncefield, Hakan Burden, and Rogardt Heldal. Industrial Adoption of Model-Driven Engineering: Are the Tools Really the Problem? In *Proceedings of the 16th International Conference on Model Driven Engineering Languages and Systems (MODELS)* 2013. ACM, 2013.

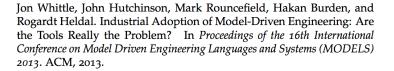
#### **Study Findings II**

Complexity problems are typically associated with offthe- shelf tools. Of particular note is accidental complexity – which can be introduced due to poor consideration of other categories, such as lack of flexibility to adapt the tools to a company's own context [..]

Jon Whittle, John Hutchinson, Mark Rouncefield, Hakan Burden, and Rogardt Heldal. Industrial Adoption of Model-Driven Engineering: Are the Tools Really the Problem? In *Proceedings of the 16th International Conference on Model Driven Engineering Languages and Systems (MODELS)* 2013. ACM, 2013.

#### **Study Findings II**

Complexity problems are typically associated with offthe- shelf tools. Of particular note is accidental complexity — which can be introduced due to poor consideration of other categories, such as lack of flexibility to adapt the tools to a company's own context [...]



Typical Features
Used by the tool vendor
to
build the initial tool
(languages).

**Typical Features** Used by the tool vendor to build the initial tool Useduzges, end user to adapt the tool (lang extensions)!

**Typical Features** Used by the tool vendor to build the initial tool Useduzges, end user to adapt the tool (lang extensions)! Extensions are firstclass!

Adaptability is built-in!

### Extensio

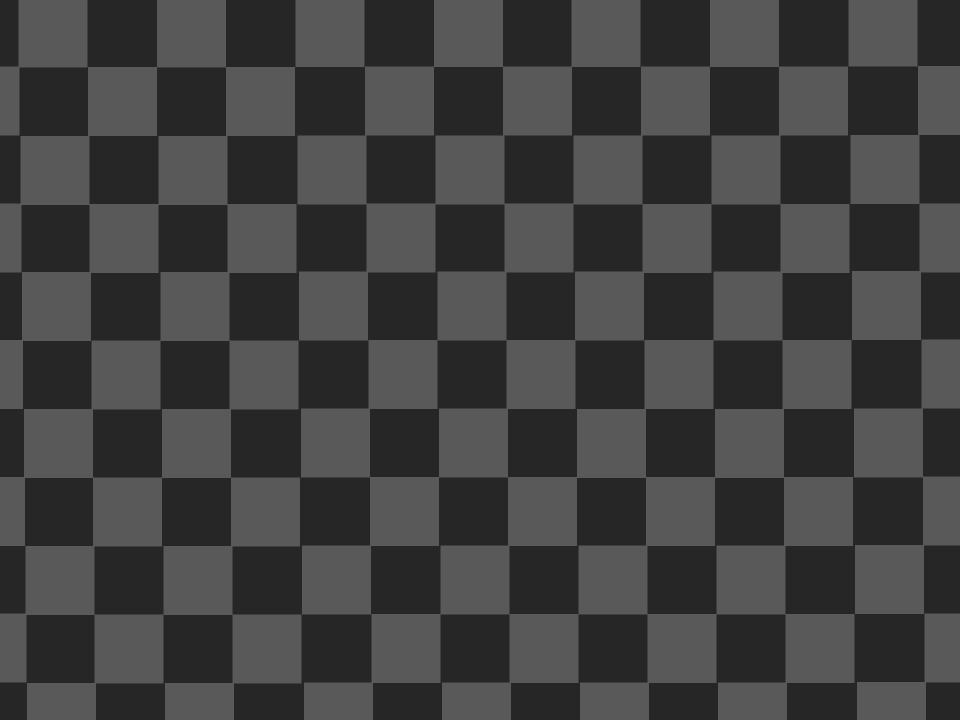
ns art-clas

Adaptability is built-in!

### Extensio

ns art-clas

Fundamentally different from Today's State-of-the-Art in Tools





## An Example

#### An Example System

Language Engineering Embedded Software



Specific languages



A collection of integrated fanguage Engineering Embedded Software fanguage Engineering Embedded Engineering Embedd

Specific

andliades



# A collection of integrated for embedded software fanguage Engineering Embedded Software for embedded software engineering

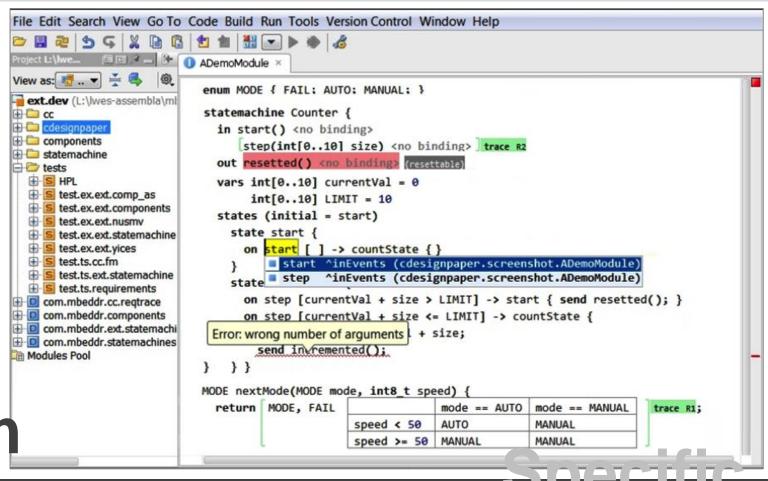
User Extensions		to be lined by users									
Default Extensions	Test Support						Glossaries	Use Cases & Scenarios			
	Compo- nents	Physical Units	State Machines	State Machin Verification		Contracts					
Core		C core		Model Checking	SMT Solving	Dataflow Analysis	Visual- ization	PLE Variability	Documen- tation	Requirements Tracing	. &
Platform	JetBrains MPS										
Backend Tool	C Compiler, Debugger and Importer			NuSMV	Yices	СВМС	PlantUM	1L			
	Imple	Implementation Concern Analysis Concern				Process Concern					

l anduades



#### Language Engineering Embedded Software

An IDE for all Of them



landuades



Language Engineering Embedded Software

**Open Source Eclipse Public License** 

http://mbeddr.com

itemis fortiss







landuades

#### **Built on JetBrains MPS**



#### **Built on JetBrains MPS**



JetBRAINS

**Projectional Editing** 

Textual/Symbolic/Tabular/(soon Graphical)

Multiple projections for the same language (in 3.0, due soon)

Modular language development, extension and embedding

### VS

#### **Built on JetBrains MPS**

Support for language aspects such as type system, scopes, code completion, find usages, dataflow

Template-based approach for transformation and code generation with IDE support for target language in templates

Support for building extensible debuggers

#### **Built on JetBrains MPS**





```
File Edit Search View Go To Code Build Run Tools Version Control Window Help
                   Project L:\hwe... 🗇 🖾 🕒 🕪 🕦 ADemoModule ×
View as: 📲 .. 🔻 🚆 🚭
                            enum MODE { FAIL: AUTO: MANUAL: }
ext.dev (L:\lwes-assembla\ml
                            statemachine Counter {
E CC
designpaper
                              in start() <no binding>
components
                                  step(int[0..10] size) <no binding> trace R2
statemachine
                              out resetted() <no binding> (resettable)
tests
  H-S HPL
                              vars int[0..10] currentVal = 0
  s test.ex.ext.comp as
                                   int[0..10] LIMIT = 10

    test.ex.ext.components

                              states (initial = start)
  E test.ex.ext.nusmv
                                state start {

    test.ex.ext.statemachine

                                  on start [ ] -> countState { }

    test.ex.ext.yices

  ⊞ S test.ts.cc.fm
                                     start ^inEvents (cdesignpaper.screenshot.ADemoModule)
                                state step ^inEvents (cdesignpaper.screenshot.ADemoModule)
  on step [currentVal + size > LIMIT] -> start { send resetted(); }

    com.mbeddr.cc.regtrace

  com.mbeddr.components
                                  on step [currentVal + size <= LIMIT] -> countState {
  com.mbeddr.ext.statemachi
                             Error: wrong number of arguments | + size;
  com.mbeddr.statemachines
                                    send in remented();
Modules Pool
                            MODE nextMode(MODE mode, int8 t speed) {
                              return MODE, FAIL
                                                                             mode == MANUAL
                                                               mode == AUTO
                                                                                               trace R1;
                                                  speed < 50
                                                               AUTO
                                                                             MANUAL
                                                  speed >= 50
                                                               MANUAL
                                                                             MANUAL
```

#### **Built on JetBrains MPS**

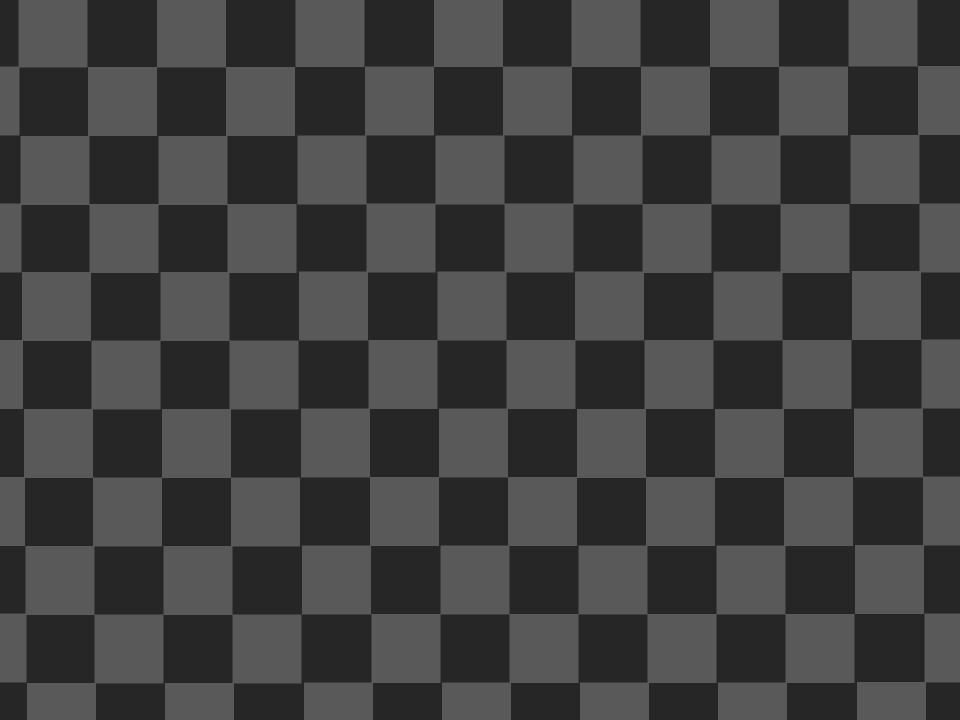




Open Source Apache 2.0

http://jetbrains.com/mps

## DEMO





## Summing up

**Key Points** 

To build meaningful tools, the data must be extended.

Extending the tool Wights,) is not

**Key Points** 

# Structured Data can be expressed as languages.

Languages are data nlus syntax

**Key Points** 

# Language Engineering supports extension and composition

This supports for supports an appropriate the supports are supported as a support of the support

**Key Points** 

IDE-style tools are very good for editing data/programs.

We've got a lot of Expresellar

**Key Points** 

Language Workbenches are the key enabling technology.

MPS is IMHO the most feeling it it is not the

**Key Points** 

## Let's build new classes of tools!

... which make meximality a reality



### The End.



voelter.de dslbook.org mbeddr.com jetbrains.com/mps

### The End.